

Lecture 4: GMM Estimation

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Outline

- Asset Pricing
 - General Formulas
 - GMM for regressions
 - 2-stage Estimation
- 1 Applying GMM
 - Instruments
 - Testing
 - Prespecified weighting matrix W and spectral matrix S
 - Alternative Weighting Matrix
 - Estimating the Spectral Density Matrix
 - 2 Consumption-CAPM

- model:

$$E[f(x_t, b)] = 0$$

where f represents a vector of sample moments, x_t can be vector of M data series, b is a vector of N parameters

- GMM estimate: choose \hat{b} such that

$$a_T g_T(\hat{b}) = 0$$

where $g_T(\hat{b}) = (1/T) \sum_{t=1}^T f(x_t, \hat{b})$

GMM: An Example

- Find the parameters b such that

$$P = E[MX]$$

is satisfied.

- For example, in the CCAPM,

$$b \equiv [\beta \ \gamma]$$

and

$$M = \beta(C_{t+1}/C_t)^{-\gamma}$$

- See at <http://mcliff.cob.vt.edu/> Mike Cliff's GMM software package in Matlab.

Asset Pricing Models

- Any asset pricing model implies the moment condition:

$$E[M_{t+1}R_{t+1} - 1] = 0.$$

- Define the pricing errors $u_t(b)$ as $u_t(b) \equiv M_{t+1}R_{t+1} - 1$.
- $g_T(b)$ is the sample mean of the errors u_t :

$$g_T(b) \equiv E_T[u_t(b)] = \frac{1}{T} \sum_{t=1}^T u_t(b).$$

- GMM chooses b to make the pricing errors as small as possible:

$$\text{min}_T(b)' W g_T(b)$$

for some weighting matrix W

- first-stage GMM chooses b to make the pricing errors as small as possible:

$$\hat{b}_1 = g_T(b)' W g_T(b)$$

for some arbitrary weighting matrix W , e.g. $W = I$

Asset Pricing Models

- second-stage GMM chooses b to make the pricing errors as small as possible:

$$\hat{b}_2 = g_T(b)' S^{-1} g_T(b)$$

where S is defined as:

$$S = \sum_{j=-\infty}^{\infty} E [u_t(b) u_{t-j}(b)']$$

- asymptotically normal
- asymptotically efficient
- consistent

- The Consumption-CAPM implies the moment condition:

$$E[\beta(C_{t+1}/C_t)^{-\gamma}R_{t+1} - 1] = 0.$$

- Define the pricing errors $u_t(\gamma, \beta)$ as
 $u_t(\gamma, \beta) \equiv \beta(C_{t+1}/C_t)^{-\gamma}R_{t+1} - 1.$
- $g_T(\gamma, \beta)$ is the sample mean of the errors u_t :

$$g_T(\gamma, \beta) \equiv E_T[u_t(\gamma, \beta)] = \frac{1}{T} \sum_{t=1}^T u_t(\gamma, \beta).$$

- GMM chooses b to make the pricing errors as small as possible:

$$\min_{\gamma, \beta} g_T(\gamma, \beta)' W g_T(\gamma, \beta)$$

for some weighting matrix W

Pricing Error

- $g_T(b)$ can be interpreted as a *pricing error*:

$$g(b) = E[MR^i - 1] = E(M) \left[\underbrace{E(R^i)}_{\text{actual mean return}} - \underbrace{\left(-\frac{\text{cov}(M, R^i) - 1}{E(M)} \right)}_{\text{predicted mean return}} \right]$$

$$= \frac{1}{R^f} \alpha_i.$$

with α_i denoting *Jensen's alpha*

- Express a model as

$$E[f(x_t, b)] = 0$$

- The general GMM estimate \hat{b} sets a linear combination of the pricing errors to zero:

$$a_T g_T(\hat{b}) = 0,$$

where

$$g_T(b) \equiv \frac{1}{T} \sum_{t=1}^T f(x_t, b),$$

and a_T is a matrix that defines which linear combination of $g_T(b)$ will be set to zero.

Distribution of Estimates

- the asymptotic distribution of the GMM estimate is:

$$\sqrt{T}(\hat{b} - b) \rightarrow N[0, (ad)^{-1} a S a' (ad)^{-1'}],$$

where

$$\begin{aligned} d &\equiv E\left[\frac{\partial f}{\partial b'}(x_t, b)\right] = \frac{\partial g_T(b)}{\partial b'}, \\ a &\equiv a_T, \\ S &\equiv \sum_{j=-\infty}^{\infty} E[f(x_t, b)f(x_{t-j}, b)']. \end{aligned}$$

- Hansen82b gives us the sampling distribution of the moments $g_T(b)$:

$$\sqrt{T}g_T(\hat{b}) \rightarrow N[0, (I - d(ad)^{-1}a)S(I - d(ad)^{-1}a)'].$$

- The efficient estimate is obtained by setting:

$$a = d'S^{-1}$$

In this case,

$$\begin{aligned}\sqrt{T}(\hat{b} - b) &\rightarrow N[0, (d'S^{-1}d)^{-1}], \\ TJ_T = Tg_T(\hat{b})'S^{-1}g_T(\hat{b}) &= \chi^2(\#moments - \#parameters), \\ TJ_T(\text{restricted}) - TJ_T(\text{unrestricted}) &= \chi^2(\#restrictions).\end{aligned}$$

OLS as GMM

- A familiar example: minimize the following objective function.

$$\text{Min}_{\beta} E_T[(y_t - \beta'x_t)^2]$$

Result

The OLS estimator satisfies:

$$\begin{aligned}f(x_t, \beta) &= x_t(y_t - \beta'x_t) = x_t\varepsilon_t, \\ g_T(\beta) &= E_T[x_t(y_t - \beta'x_t)], \\ a_T &= I, \\ d &= -E_T[x_t x_t'], \\ \hat{\beta} &= E_T[x_t x_t']^{-1} E_T[x_t y_t] \\ \text{var}(\hat{\beta}) &= \frac{1}{T} E_T[x_t x_t']^{-1} \left[\sum_{j=-\infty}^{\infty} E(\varepsilon_t x_t x_{t-j}' \varepsilon_{t-j}') \right] E_T[x_t x_t']^{-1}\end{aligned}$$

Serially Uncorrelated

- OLS assumptions
- assume the errors are serially uncorrelated and homoscedastic:

$$E[\varepsilon_t | x_t, x_{t-1}, \dots, \varepsilon_t, \varepsilon_{t-1}, \dots] = 0$$
$$E[\varepsilon_t^2 | x_t, x_{t-1}, \dots, \varepsilon_t, \varepsilon_{t-1}, \dots] = \sigma_e^2$$

- this implies that

$$\sum_{j=-\infty}^{\infty} E(\varepsilon_t x_t x'_{t-j} \varepsilon'_{t-j}) = E[\varepsilon_t^2 x_t x'_t] = \sigma_e^2 E[x_t x'_t]$$

- this in turn implies that:

$$\text{var}(\hat{\beta}) = \frac{1}{T} \sigma_e^2 E_T[x_t x'_t]^{-1} = \sigma_e^2 \left[\sum_{t=1}^T (x_t x'_t) \right]^{-1}$$

Heteroscedastic Errors

- assume the errors are serially uncorrelated and homoscedastic:

$$E[\varepsilon_t | x_t, x_{t-1}, \dots, \varepsilon_t, \varepsilon_{t-1}, \dots] = 0$$
$$E[\varepsilon_t^2 | x_t, x_{t-1}, \dots, \varepsilon_t, \varepsilon_{t-1}, \dots] = \sigma_e^2$$

- this implies that

$$\sum_{j=-\infty}^{\infty} E(\varepsilon_t x_t x'_{t-j} \varepsilon'_{t-j}) = E[\varepsilon_t^2 x_t x'_t] = \sigma_e^2 E[x_t x'_t]$$

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- the heteroskedasticity-consistent standard errors:

$$\text{var}(\hat{\beta}) = \frac{1}{T} E_T[x_t x_t']^{-1} [E(\varepsilon_t^2 x_t x_t')] E_T[x_t x_t']^{-1}$$

Overlapping Return Data

- Hansen-Hodrick:

$$y_{t+k} = \beta_k' x_t + \varepsilon_{t+k}, t = 1, 2, \dots, T$$

- under the null of no forecastability, there is still correlation in varepsilon_{t+k} :

$$E(\varepsilon_t \varepsilon_{t-j}) = 0, |j| \leq k$$

- standard errors are:

$$\text{var}(\hat{\beta}_k) = \frac{1}{T} E_T[x_t x_t']^{-1} \left[\sum_{j=-k}^k E(\varepsilon_t x_t x_{t-j}' \varepsilon_{t-j}') \right] E_T[x_t x_t']^{-1}$$

- the heteroskedasticity-consistent standard errors:

$$\text{var}(\hat{\beta}) = \frac{1}{T} E_T[x_t x_t']^{-1} [E(\varepsilon_t^2 x_t x_t')] E_T[x_t x_t']^{-1}$$

1st-stage

- A first stage estimate of b can be obtained by minimizing a quadratic form of the sample mean of the errors:

$$\hat{b}_1 = \text{argmin}_b g_T(b)' W g_T(b).$$

- This estimate is consistent and asymptotically normal.
- use $W = I$ in 1st stage
- The first-order conditions are:

$$\frac{\partial g_T'}{\partial b} W g_T(b) = 0.$$

- Using \hat{b}_1 , we can form an estimate \hat{S} of

$$S \equiv \sum_{j=-\infty}^{\infty} E[u_t(\hat{b}_1) u_{t-j}(\hat{b}_1)']$$

evaluated at the first stage estimate.

- A second stage estimate of \hat{b} is obtained as:

$$\hat{b}_2 = \operatorname{argmin}_b g_T(b)' S^{-1} g_T(b).$$

\hat{b}_2 is consistent, asymptotically normal and efficient.

- The variance-covariance matrix of \hat{b}_2 is:

$$\operatorname{var}(\hat{b}_2) = \frac{1}{T} (d' S^{-1} d)^{-1},$$

where

$$d \equiv \frac{\partial g_T(b)}{\partial b} = E_T \left(\frac{\partial}{\partial b} [M_{t+1} R_{t+1} - 1] \right) \Big|_{b=\hat{b}}.$$

Variance of the Mean

- the covariance matrix of $g_T(b)$ is the variance of a sample mean.
- Exploiting the assumption that $E(u_t) = 0$ and that u_t is covariance stationary ($E(u_t u_{t-j})$ does not depend on t) leads to:

$$\begin{aligned} \operatorname{var}(g_T) &= \operatorname{var}\left(\frac{1}{T} \sum_{t=1}^T u_{t+1}\right) \\ &= \frac{1}{T^2} [TE(u_t u_t') + (T-1)(E(u_t u_{t-1}') + E(u_t u_{t+1}')) + \dots]. \end{aligned}$$

- As $T \rightarrow \infty$, $(T-j)/T \rightarrow 1$, so:

$$\operatorname{var}(g_T) \rightarrow \frac{1}{T} \sum_{j=-\infty}^{\infty} E(u_t u_{t-j}') = \frac{1}{T} S.$$

- when the u_t are uncorrelated over time ($E[u_t u_{t-j}] = 0$), then:

$$\text{var}(g_T) = \text{var}\left(\frac{1}{T} \sum_{t=1}^T u_{t+1}\right) = \frac{1}{T} E(u_t u_t') = \frac{\text{var}(u)}{T}.$$

- standard error on sample mean is given by:

$$\sigma(u) / \sqrt{T}$$

Which Moments to Pick?

- GMM minimizes a weighted sum of squared pricing errors
- Some assets may have much more variance than others.
- For those assets, the sample mean $g_T = E_T(MR - 1)$ will be a much less accurate measurement of the population mean $E(MR - 1)$, since the sample mean will vary more from sample to sample.
- second stage picks the linear combination of pricing errors that are **best measured** (smallest sampling variation)

- optimal weighting matrix W

$$\hat{b}_2 = \operatorname{argmin}_b g_T(b)' W g_T(b).$$

- optimal to set

$$W = S^{-1}$$

with

$$S \equiv \sum_{j=-\infty}^{\infty} E(u_t u'_{t-j})$$

- put less weight on moments which are not measured as accurately

Delta Method

- consider the scalar case
- think of the delta method: the variance of

$$f(x) \cong f'(x)^2 \operatorname{var}(x)$$

- Here, S/T is the variance of g_T .
- Think of b as a function of g_T .
- define $\frac{\partial b}{\partial g_T} = \left[\frac{\partial g_T}{\partial b} \right]^{-1} = d^{-1}$.
- Then the variance is:

$$\operatorname{var}(\hat{b}_2) = \frac{\partial b}{\partial g_T} \operatorname{var}(g_T) \frac{\partial b}{\partial g_T}.$$

- test asset pricing models on returns:

$$E[M_{t+1}(b)R_{t+1} - 1] = 0$$

- add instruments:

$$E\{[M_{t+1}(b)R_{t+1} - 1] \otimes z_t\} = 0$$

Instruments

- add instruments:

$$E \left\{ \begin{bmatrix} M_{t+1}(b)R_{t+1}^1 \\ M_{t+1}(b)R_{t+1}^2 \\ M_{t+1}(b)R_{t+1}^1 z_t \\ M_{t+1}(b)R_{t+1}^2 z_t \end{bmatrix} - \begin{bmatrix} 1 \\ 1 \\ z_t \\ z_t \end{bmatrix} \right\} = 0$$

- check that

$$u_{t+1} = M_{t+1}R_{t+1} - 1$$

is conditionally and unconditionally mean zero

- check that discounted return is unforecastable

$$E(z_t u_{t+1}) = 0$$

- testing of a single coefficient

- $\hat{b}_i / \sqrt{\text{var}(\hat{b})_{ii}} \sim N(0, 1)$
- form the usual χ^2 test:

$$\hat{b}'_i [\text{var}(\hat{b})_{ii}]^{-1} \hat{b}_i \sim \chi^2(\text{\#included } b).$$

- test of the overall fit of the model: are the pricing errors large?

$$TJ_T = T[g_T(\hat{b})' S^{-1} g_T(\hat{b})] \sim \chi^2(\text{\#moments} - \text{\#parameters}).$$

- if we would not observe pricing errors this size very often if the model were true, then we reject the model!

Stationarity

- GMM relies on stationarity: the joint distribution of x_t and x_{t-j} only depends on j
- choose test assets with stationarity in mind:
 - e.g. IBM started out as a growth stock, now it's a value stock
 - sort individual stocks into portfolios based on characteristics

- GMM focuses on statistically informative moments
- Economically interesting moments?
 - The spectral density matrix S is often nearly singular (asset returns are highly correlated with each other).
 - we're interested in the pricing errors on the portfolios, not in pricing errors on arbitrary portfolios of these portfolios
 - GMM tends to focus on the **sample** minimum variance portfolios
- weighting matrix changes as parameters and model changes
- use fixed and pre-specified weighting matrices when comparing different models (e.g. comparing J -stats)

Example

- suppose that:

$$S = \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix};$$
$$S^{-1} = \frac{1}{1-\rho^2} \begin{pmatrix} 1 & -\rho \\ -\rho & 1 \end{pmatrix}.$$

Then $S^{-1} = C'C$, where (assume $\rho = 0.95$ for a numerical example):

$$C = \begin{pmatrix} \frac{1}{\sqrt{1-\rho^2}} & \frac{-\rho}{\sqrt{1-\rho^2}} \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 3.2 & -3.04 \\ 0 & 1 \end{pmatrix}.$$

- GMM minimizes

$$(g_T' C')(C g_T)$$

Second moment matrix

- instead of S^{-1} use

$$W = E(XX')^{-1}$$

- HansenJagannathan97

Result

the minimum distance between a candidate discount factor Y and the space of true discount factors the same as the minimum value of the GMM criterion with $W = E(XX')^{-1}$.

Second moment matrix

- Using the same notations as in the previous chapter:

$$\text{proj}(Y|\underline{X}) = E(YX')E(XX')^{-1}X.$$

The SDF X^* is

$$X^* = P'E(XX')^{-1}X$$

- the distance between Y and the nearest valid M is:

$$\begin{aligned} \|Y - \text{nearest } M\| &= \|\text{proj}(Y|\underline{X}) - X^*\|, \\ &= \|E(YX')E(XX')^{-1}X - P'E(XX')^{-1}X\|, \\ &= \|(E(YX') - P')E(XX')^{-1}X\|, \\ &= [E(Y'X) - P]'E(XX')^{-1}[E(Y'X) - P] \\ &= g_T'E(XX')^{-1}g_T. \end{aligned}$$

Spectral Density matrix

- Estimating the spectral density matrix

$$S \equiv \sum_{j=-\infty}^{\infty} E[u_t u'_{t-j}]$$

where $u_t \equiv M_t(b)R_t - 1$.

- 1 Use a sensible first-stage W or transform the data: think $W = I$, check units and correlation of returns.
- 2 Remove means: under the null, $E(u_t) = 0$.
 - Estimate $\bar{u} \equiv \frac{1}{T} \sum_{t=1}^T u_t$.
- 3 Down-weight higher-order correlations: NeweyWest estimator:

$$\hat{S} = \sum_{j=-k}^k \frac{k-|j|}{k} \frac{1}{T} \sum_{t=1}^T u_t u'_{t-j}.$$

Spectral Density matrix

- The Newey-West estimator can be thought as the variance of k th sums:

$$\begin{aligned} \text{var}\left(\frac{1}{k} \sum_{j=-k}^k u_{t-j}\right) &= \frac{1}{k^2} [kE(u_t u'_t) + (k-1)(E(u_t u'_{t-1}) + E(u_{t-1} u_t)) \\ &+ \dots + (E(u_t u'_{t-k}) + E(u_{t-k} u_t))], \\ &= \frac{1}{k} \sum_{j=-k}^k \frac{k-|j|}{k} E(u_t u'_{t-j}). \end{aligned}$$

Andrews provides an algorithm for the optimal number of lags k .

- Rely on parametric structures for autocorrelation and heteroskedasticity?

- Example: assume that u_t is an $AR(1)$: $u_t = \rho u_{t-1} + \varepsilon_t$. Then,

$$S = \sum_{j=-\infty}^{\infty} E[u_t u'_{t-j}] = \frac{\sigma_u^2}{1-\rho^2} \sum_{j=-\infty}^{\infty} \rho^{|j|} = \frac{\sigma_u^2}{1-\rho^2} \frac{1+\rho}{1-\rho}.$$

- Use the null to limit correlations? The Euler equation gives $E_t(M_{t+1}R_{t+1} - 1) = E_t(u_{t+1}) = 0$. This implies that $E_t(u_t u'_{t-j}) = 0$ for $j \neq 0$ and:

$$S = \frac{1}{T} \sum_{t=1}^T u_t u'_t.$$

Iterating on S

- Iteration: The second stage estimate \hat{b}_2 does not imply the same spectral density matrix. Search for a fixed point?

$$\hat{b}_3 = \operatorname{argmin}_b g_T(b)' S(\hat{b}_2)^{-1} g_T(b).$$

- Continuously updating estimator - see HansenHeatonYaron:

$$\hat{b} = \operatorname{argmin}_b g_T(b)' S(b)^{-1} g_T(b).$$

- The Consumption-CAPM implies the moment condition:

$$E \left[(\beta(C_{t+1}/C_t)^\alpha R_{t+1} - 1) \otimes z_t \right] = 0.$$

- Define the pricing errors $u_t(\alpha, \beta)$ as

$$u_t(\alpha, \beta) \equiv (\beta(C_{t+1}/C_t)^\alpha R_{t+1} - 1) \otimes z_t$$

- $g_T(\gamma, \beta)$ is the sample mean of the errors u_t :

$$g_T(\gamma, \beta) \equiv E_T[u_t(\alpha, \beta)] = \frac{1}{T} \sum_{t=1}^T u_t(\alpha, \beta).$$

- GMM chooses b to make the pricing errors as small as possible:

$$\min_{\alpha, \beta} g_T(\gamma, \beta)' W g_T(\alpha, \beta)$$

- HS use the optimal weighting matrix